

# Regret bounds for generalized Bayes updates

Pierre Alquier



Center for  
Advanced Intelligence Project

AI seminar series – UCL AI Centre – May 19, 2021

# The sequential prediction problem

## Sequential prediction problem

# The sequential prediction problem

## Sequential prediction problem

- ➊ ➊  $x_1$  given

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
  - ② predict  $y_1 : \hat{y}_1$
  - ③  $y_1$  is revealed
- 
- ② ①  $x_2$  given

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed
  
- ③ ①  $x_3$  given

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed
  
- ③ ①  $x_3$  given
- ② predict  $y_3 : \hat{y}_3$

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given  
② predict  $y_1 : \hat{y}_1$   
③  $y_1$  revealed
- ② ①  $x_2$  given  
② predict  $y_2 : \hat{y}_2$   
③  $y_2$  revealed
- ③ ①  $x_3$  given  
② predict  $y_3 : \hat{y}_3$   
③  $y_3$  revealed
- ④ ...

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed
  
- ③ ①  $x_3$  given
- ② predict  $y_3 : \hat{y}_3$
- ③  $y_3$  revealed
  
- ④ ...

**Objective :**

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  is revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed
  
- ③ ①  $x_3$  given
- ② predict  $y_3 : \hat{y}_3$
- ③  $y_3$  revealed
  
- ④ ...

**Objective :** make sure that we learn to predict well as soon as possible.

# The sequential prediction problem

## Sequential prediction problem

- ① ①  $x_1$  given
- ② predict  $y_1 : \hat{y}_1$
- ③  $y_1$  revealed
  
- ② ①  $x_2$  given
- ② predict  $y_2 : \hat{y}_2$
- ③  $y_2$  revealed
  
- ③ ①  $x_3$  given
- ② predict  $y_3 : \hat{y}_3$
- ③  $y_3$  revealed
  
- ④ ...

**Objective** : make sure that we learn to predict well **as soon as possible**. Keep

$$\sum_{t=1}^T \ell(\hat{y}_t, y_t)$$

as small as possible.

# 1st approach : “follow the regularized leader”

- set of predictors :  $\{f_\theta, \theta \in \Theta\}$ .
- $\ell_t(\theta) := \ell(f_\theta(x_t), y_t)$ .

## 1st approach : “follow the regularized leader”

- set of predictors :  $\{f_\theta, \theta \in \Theta\}$ .
- $\ell_t(\theta) := \ell(f_\theta(x_t), y_t)$ .

## Follow The Regularized Leader – FTRL

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \ell_s(\theta) + \frac{\text{pen}(\theta)}{\eta} \right\}.$$

## 1st approach : “follow the regularized leader”

- set of predictors :  $\{f_\theta, \theta \in \Theta\}$ .
- $\ell_t(\theta) := \ell(f_\theta(x_t), y_t)$ .

## Follow The Regularized Leader – FTRL

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \ell_s(\theta) + \frac{\text{pen}(\theta)}{\eta} \right\}.$$

Quadratic penalty + linearization :

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \langle \theta, \nabla \ell_s(\theta^s) \rangle + \frac{\|\theta\|^2}{2\eta} \right\}.$$

## 1st approach : “follow the regularized leader”

- set of predictors :  $\{f_\theta, \theta \in \Theta\}$ .
- $\ell_t(\theta) := \ell(f_\theta(x_t), y_t)$ .

## Follow The Regularized Leader – FTRL

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \ell_s(\theta) + \frac{\text{pen}(\theta)}{\eta} \right\}.$$

Differentiate :

$$0 = \sum_{s=1}^{t-1} \nabla \ell_s(\theta^s) + \frac{\theta^t}{\eta}.$$

## 1st approach : “follow the regularized leader”

- set of predictors :  $\{f_\theta, \theta \in \Theta\}$ .
- $\ell_t(\theta) := \ell(f_\theta(x_t), y_t)$ .

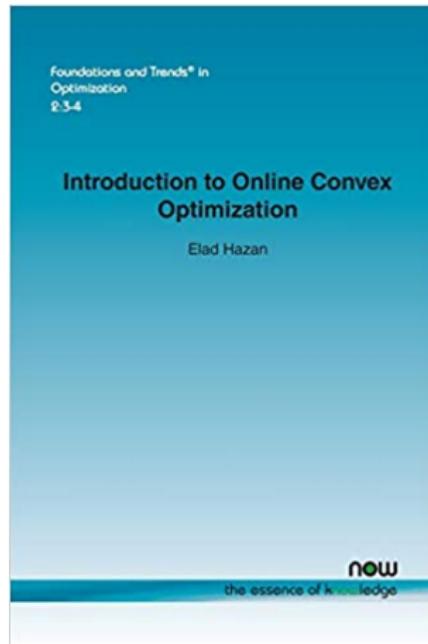
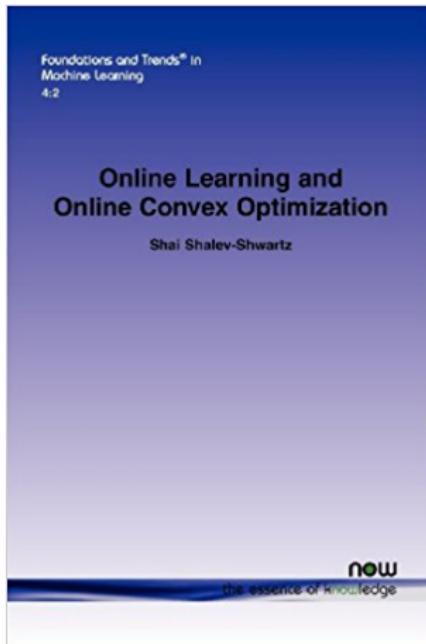
## Follow The Regularized Leader – FTRL

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \ell_s(\theta) + \frac{\text{pen}(\theta)}{\eta} \right\}.$$

## Online Gradient Algorithm – OGA

$$\theta^t := \theta^{t-1} - \eta \nabla \ell_{t-1}(\theta^{t-1}).$$

# Theoretical properties of FTRL & OGA



## 2nd approach : (generalized) Bayes

Generalized Bayes, multiplicative  
weights, Exponential Weight  
Aggregation (EWA)...

### EWA

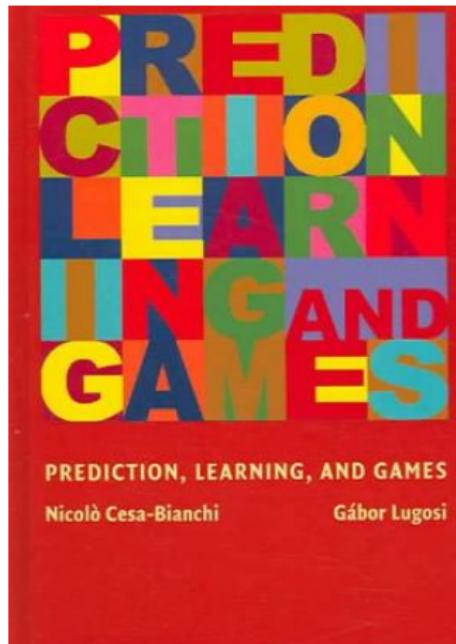
$$\rho^t(\theta) \propto \exp \left[ -\eta \sum_{s=1}^{t-1} \ell_s(\theta) \right] \pi(\theta)$$

## 2nd approach : (generalized) Bayes

Generalized Bayes, multiplicative weights, Exponential Weight Aggregation (EWA)...

EWA

$$\rho^t(\theta) \propto \exp \left[ -\eta \sum_{s=1}^{t-1} \ell_s(\theta) \right] \pi(\theta)$$



# EWA as FTRL

It is known that

$$\rho^t = \arg \min_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{s=1}^{t-1} \underbrace{\mathbb{E}_{\theta \sim \rho} [\ell_s(\theta)]}_{=: L_s(\rho)} + \underbrace{\frac{\text{KL}(\rho \| \pi)}{\eta}}_{=: \frac{\text{pen}(\rho)}{\eta}} \right\}.$$

That is, EWA is a special case of FTRL.

$$\text{KL}(\rho \| \pi) = \begin{cases} \mathbb{E}_{\theta \sim \rho} \left[ \log \left( \frac{d\rho}{d\pi}(\theta) \right) \right] & \text{if } \rho \ll \pi \\ +\infty & \text{otherwise.} \end{cases}$$

## 1st objective

We will study a more general version of FTRL on  $\rho$  :

$$\rho^t = \arg \min_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{s=1}^{t-1} \mathbb{E}_{\theta \sim \rho} [\ell_s(\theta)] + \frac{D(\rho \| \pi)}{\eta} \right\},$$

for more general divergences  $D$ .



P. Alquier. *Non-exponentially Weighted Aggregation : Regret Bounds for Unbounded Loss Functions*. Accepted for ICML 2021.

## 2nd objective

EWA is often non feasible in practice. We will thus modify it : we will constrain  $\rho^t$  to belong to a feasible set of probability distributions (e.g. : Gaussian).



B.-E. Chérif-Abdellatif, P. Alquier, M. E. Khan (2019). *A regret bound for online variational inference*. 11th Asian Conference on Machine Learning (ACML).

# Co-authors

Badr-Eddine  
Chérief-Abdellatif



Emtiyaz Khan



Riken

AIP

Center for  
Advanced Intelligence Project

Approximate Bayesian Inference team

<https://team-approx-bayes.github.io/>

## 1 Generalized Bayes update

- Formula for the posterior : non-exponential weights
- Regret bound

## 2 Online variational inference

- The algorithms : SVA and SVB
- Regret bounds

## 1 Generalized Bayes update

- Formula for the posterior : non-exponential weights
- Regret bound

## 2 Online variational inference

- The algorithms : SVA and SVB
- Regret bounds

## Reminder

$$\rho^t = \arg \min_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{s=1}^{t-1} \mathbb{E}_{\theta \sim \rho} [\ell_s(\theta)] + \frac{D_\phi(\rho \| \pi)}{\eta} \right\},$$

## Reminder

$$\rho^t = \arg \min_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{s=1}^{t-1} \mathbb{E}_{\theta \sim \rho} [\ell_s(\theta)] + \frac{D_\phi(\rho \| \pi)}{\eta} \right\},$$

where

$$D_\phi(\rho \| \pi) = \begin{cases} \mathbb{E}_{\theta \sim \pi} [\phi(\frac{d\rho}{d\pi}(\theta))] & \text{if } \rho \ll \pi \\ +\infty & \text{otherwise,} \end{cases}$$

and  $\phi : \mathbb{R}_+ \rightarrow \mathbb{R} \cup \{+\infty\}$  with :

- $\phi$  convex,
- $\phi(1) = 0$ ,
- $\inf_{x \geq 0} \phi(x) > -\infty$ .

# Differential of the convex conjugate

Assume that  $\phi$  is differentiable, strictly convex. Put

$$\tilde{\phi}(x) = \begin{cases} \phi(x) & \text{if } x \geq 0, \\ +\infty & \text{if } x < 0. \end{cases}$$

# Differential of the convex conjugate

Assume that  $\phi$  is differentiable, strictly convex. Put

$$\tilde{\phi}(x) = \begin{cases} \phi(x) & \text{if } x \geq 0, \\ +\infty & \text{if } x < 0. \end{cases}$$

Then

$$\tilde{\phi}^* = \sup_{x \in \mathbb{R}} [xy - \tilde{\phi}(x)] = \sup_{x \geq 0} [xy - \phi(x)]$$

is differentiable and for any  $y \in \mathbb{R}$ ,

$$\nabla \tilde{\phi}^*(y) = \arg \max_{x \geq 0} \{xy - \phi(x)\}.$$

Formula for  $\rho^t$ 

Assume moreover that  $\tilde{\phi}^*(\lambda - a) - \lambda \rightarrow \infty$  when  $\lambda \rightarrow \infty$ , for any  $a \geq 0$ . Then :

$$\lambda_t = \arg \min_{\lambda \in \mathbb{R}} \left\{ \int \tilde{\phi}^* \left( \lambda - \eta \sum_{s=1}^{t-1} \ell_s(\theta) \right) \pi(d\theta) - \lambda \right\}$$

exists, and

$$\rho^t(d\theta) = \nabla \tilde{\phi}^* \left( \lambda_t - \eta \sum_{s=1}^{t-1} \ell_s(\theta) \right) \pi(d\theta).$$

# The classical example : KL and exponential weights

- $\phi(x) = x \log(x),$

# The classical example : KL and exponential weights

- $\phi(x) = x \log(x),$
- $\tilde{\phi}^*(y) = \exp(y - 1),$

## The classical example : KL and exponential weights

- $\phi(x) = x \log(x),$
- $\tilde{\phi}^*(y) = \exp(y - 1),$
- $\nabla \tilde{\phi}^*(y) = \exp(y - 1),$

## The classical example : KL and exponential weights

- $\phi(x) = x \log(x),$
- $\tilde{\phi}^*(y) = \exp(y - 1),$
- $\nabla \tilde{\phi}^*(y) = \exp(y - 1),$

$$\rho^t(d\theta) = \exp \left[ \lambda_t - \eta \sum_{s=1}^{t-1} \ell_s(\theta) - 1 \right] \pi(d\theta).$$

## The classical example : KL and exponential weights

- $\phi(x) = x \log(x),$
- $\tilde{\phi}^*(y) = \exp(y - 1),$
- $\nabla \tilde{\phi}^*(y) = \exp(y - 1),$

$$\rho^t(d\theta) = \exp \left[ \lambda_t - \eta \sum_{s=1}^{t-1} \ell_s(\theta) - 1 \right] \pi(d\theta).$$

$$\rho^t(d\theta) = \frac{\exp \left[ -\eta \sum_{s=1}^{t-1} \ell_s(\theta) \right] \pi(d\theta)}{\int \exp \left[ -\eta \sum_{s=1}^{t-1} \ell_s(\vartheta) \right] \pi(d\vartheta)}.$$

# The $\chi^2$ divergence

- $\phi(x) = x^2 - 1,$

The  $\chi^2$  divergence

- $\phi(x) = x^2 - 1,$
- $\tilde{\phi}^*(y) = (y^2/4)1_{\{y \geq 0\}},$

The  $\chi^2$  divergence

- $\phi(x) = x^2 - 1,$
- $\tilde{\phi}^*(y) = (y^2/4)1_{\{y \geq 0\}},$
- $\nabla \tilde{\phi}^*(y) = (y/2)_+,$

The  $\chi^2$  divergence

- $\phi(x) = x^2 - 1,$
- $\tilde{\phi}^*(y) = (y^2/4)1_{\{y \geq 0\}},$
- $\nabla \tilde{\phi}^*(y) = (y/2)_+,$

$$\rho^t(d\theta) = \left[ \frac{\lambda_t - \eta \sum_{s=1}^{t-1} \ell_s(\theta)}{2} \right]_+ \pi(d\theta).$$

# Some references

- the formula was known for a finite  $\Theta$  :



M. D. Reid, R. M. Frongillo, R. C. Williamson, N. Mehta (2015). *Generalized mixability via entropic duality*. COLT.

- the proof for the general case relies on :



R. Agrawal, T. Horel (2020). *Optimal bounds between  $f$ -divergences and integral probability metrics*. ICML.

- comparable PAC-Bayes bounds (no online update) :



P. Alquier and B. Guedj (2018). *Simpler PAC-Bayesian bounds for hostile data*. Machine Learning.

- defense of the generalized Bayes update :



J. Knoblauch, J. Jewson, T. Damoulas (2019). *Generalized variational inference : Three arguments for deriving new posteriors..* Preprint arXiv.

- more : see the paper.

# General regret bound

Assume there is a norm  $\|\cdot\|$  such that

# General regret bound

Assume there is a norm  $\|\cdot\|$  such that

- $\rho \mapsto \mathbb{E}_{\theta \sim \rho}[\ell_t(\theta)]$  is  $L$ -Lipschitz w.r.t  $\|\cdot\|$ ,

# General regret bound

Assume there is a norm  $\|\cdot\|$  such that

- $\rho \mapsto \mathbb{E}_{\theta \sim \rho}[\ell_t(\theta)]$  is  $L$ -Lipschitz w.r.t  $\|\cdot\|$ ,
- $\rho \mapsto D_\phi(\rho\|\pi)$  is  $\alpha$ -strongly convex w.r.t  $\|\cdot\|$ .

# General regret bound

Assume there is a norm  $\|\cdot\|$  such that

- $\rho \mapsto \mathbb{E}_{\theta \sim \rho}[\ell_t(\theta)]$  is  $L$ -Lipschitz w.r.t  $\|\cdot\|$ ,
- $\rho \mapsto D_\phi(\rho\|\pi)$  is  $\alpha$ -strongly convex w.r.t  $\|\cdot\|$ .

## Theorem

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \rho^t}[\ell_t(\theta)] \leq \inf_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim \rho}[\ell_t(\theta)] + \frac{\eta L^2 T}{\alpha} + \frac{D_\phi(\rho\|\pi)}{\eta} \right\}.$$

# Bound for EWA : the conditions

- known result :  $KL(\rho\|\pi)$  is 1-strongly convex with respect to  $\|\cdot\|_{TV}$  ;

## Bound for EWA : the conditions

- known result :  $KL(\rho\|\pi)$  is 1-strongly convex with respect to  $\|\cdot\|_{TV}$  ;
- we have :

$$\begin{aligned} \left| \int \ell_t(\theta) \rho(d\theta) - \int \ell_t \rho'(d\theta) \right| &\leq \int \ell_t(\theta) \left| \frac{d\rho}{d\pi}(\theta) - \frac{d\rho'}{d\pi}(\theta) \right| \pi(d\theta) \\ &\leq L \underbrace{\int \left| \frac{d\rho}{d\pi}(\theta) - \frac{d\rho'}{d\pi}(\theta) \right| \pi(d\theta)}_{=2\|\rho-\rho'\|_{TV}} \end{aligned}$$

on the condition that  $0 \leq \ell_t(\theta) \leq L$  for any  $\theta$ .

## Bound for EWA

Assume  $0 \leq \ell_t(\theta) \leq L$  for any  $\theta, t$ , then

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \rho^t} [\ell_t(\theta)] \leq \inf_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim \rho} [\ell_t(\theta)] + \eta L^2 T + \frac{\text{KL}(\rho \| \pi)}{\eta} \right\}.$$

## Bound for EWA

Assume  $0 \leq \ell_t(\theta) \leq L$  for any  $\theta, t$ , then

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \rho^t} [\ell_t(\theta)] \leq \inf_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim \rho} [\ell_t(\theta)] + \eta L^2 T + \frac{\text{KL}(\rho \| \pi)}{\eta} \right\}.$$

(This is a well-known result).

# Bound with $\chi^2$ : the conditions

- $\phi(x) = x^2 - 1$  is 2-strongly convex so  $D_\phi$  is 2-strongly convex with respect to the  $L_2(\pi)$  norm.

# Bound with $\chi^2$ : the conditions

- $\phi(x) = x^2 - 1$  is 2-strongly convex so  $D_\phi$  is 2-strongly convex with respect to the  $L_2(\pi)$  norm.
- we have

$$\begin{aligned} \left| \int \ell_t(\theta) \rho(d\theta) - \int \ell_t \rho'(d\theta) \right| &\leq \int \ell_t(\theta) \left| \frac{d\rho}{d\pi}(\theta) - \frac{d\rho'}{d\pi}(\theta) \right| \pi(d\theta) \\ &\leq L \left( \int \left( \frac{d\rho}{d\pi}(\theta) - \frac{d\rho'}{d\pi}(\theta) \right)^2 \pi(d\theta) \right)^{1/2} \end{aligned}$$

on the condition that  $(\int \ell_t(\theta)^2 \pi(d\theta))^{1/2} \leq L$ .

Bound with  $\chi^2$ 

Assume  $\int \ell_t(\theta)^2 \pi(d\theta) \leq L^2$  for any  $t$ , then

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim \rho^t} [\ell_t(\theta)] \leq \inf_{\rho \in \mathcal{P}(\Theta)} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim \rho} [\ell_t(\theta)] + \frac{\eta L^2 T}{2} + \frac{\chi^2(\rho \| \pi)}{\eta} \right\}.$$

## 1 Generalized Bayes update

- Formula for the posterior : non-exponential weights
- Regret bound

## 2 Online variational inference

- The algorithms : SVA and SVB
- Regret bounds

# Motivation



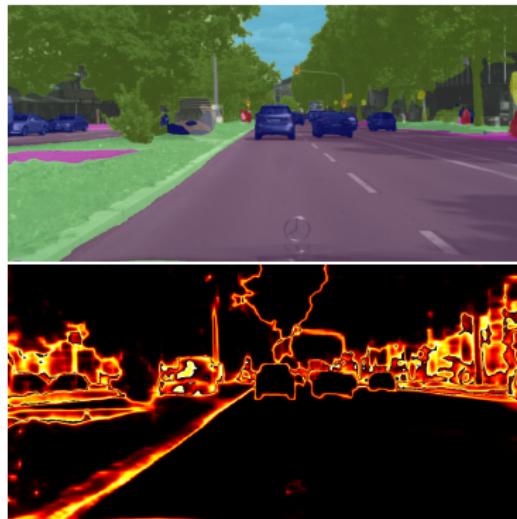
K. Osawa, S. Swaroop, A. Jain, R. Eschenhagen, R. E. Turner, R. Yokota, M. E. Khan (2019).  
*Practical Deep Learning with Bayesian Principles*. NeurIPS.

# Motivation



K. Osawa, S. Swaroop, A. Jain, R. Eschenhagen, R. E. Turner, R. Yokota, M. E. Khan (2019).  
*Practical Deep Learning with Bayesian Principles*. NeurIPS.

- ➊ proposes a fast algorithm to approximate the posterior,
- ➋ applies it to train Deep Neural Networks on CIFAR-10, ImageNet ...
- ➌ observation : improved uncertainty quantification.



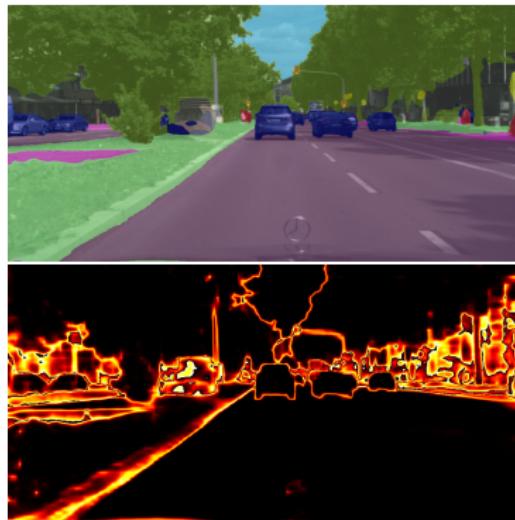
Picture : Roman Bachmann.

# Motivation



K. Osawa, S. Swaroop, A. Jain, R. Eschenhagen, R. E. Turner, R. Yokota, M. E. Khan (2019).  
*Practical Deep Learning with Bayesian Principles*. NeurIPS.

- ➊ proposes a fast algorithm to approximate the posterior,
- ➋ applies it to train Deep Neural Networks on CIFAR-10, ImageNet ...
- ➌ observation : improved uncertainty quantification.



Picture : Roman Bachmann.

**Objective :** provide a theoretical analysis of this algorithm.

# Sequential Variational Approximation (SVA)

We restrict  $\rho$  to belong to  $\mathcal{F} = \{q_\mu, \mu \in M\}$  a parametric family. Example : Gaussian distributions.

# Sequential Variational Approximation (SVA)

We restrict  $\rho$  to belong to  $\mathcal{F} = \{q_\mu, \mu \in M\}$  a parametric family. Example : Gaussian distributions.

FTRL on this set :

$$\mu^t = \arg \min_{\mu \in M} \left\{ \sum_{s=1}^{t-1} \mathbb{E}_{\theta \sim q_\mu} [\ell_s(\theta)] + \frac{D_\phi(q_\mu, \pi)}{\eta} \right\}.$$

# Sequential Variational Approximation (SVA)

We restrict  $\rho$  to belong to  $\mathcal{F} = \{q_\mu, \mu \in M\}$  a parametric family. Example : Gaussian distributions.

FTRL on this set :

$$\mu^t = \arg \min_{\mu \in M} \left\{ \sum_{s=1}^{t-1} \mathbb{E}_{\theta \sim q_\mu} [\ell_s(\theta)] + \frac{D_\phi(q_\mu, \pi)}{\eta} \right\}.$$

Linearization gives :

## SVA

$$\mu^t = \arg \min_{\mu \in M} \left\{ \sum_{s=1}^{t-1} \langle \mu, \nabla \mathbb{E}_{\theta \sim q_\mu} [\ell_s(\theta)] \rangle + \frac{D_\phi(q_\mu, \pi)}{\eta} \right\}.$$

# Streaming Variational Bayes (SVB)

(OGA) can actually be obtained via :

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \langle \theta, \nabla \ell_s(\theta^s) \rangle + \frac{\|\theta\|^2}{2\eta} \right\}$$

OR

$$\theta^t := \arg \min_{\theta} \left\{ \langle \theta, \nabla \ell_{t-1}(\theta^{t-1}) \rangle + \frac{\|\theta - \theta^{t-1}\|^2}{2\eta} \right\}$$

# Streaming Variational Bayes (SVB)

(OGA) can actually be obtained via :

$$\theta^t := \arg \min_{\theta} \left\{ \sum_{s=1}^{t-1} \langle \theta, \nabla \ell_s(\theta^s) \rangle + \frac{\|\theta\|^2}{2\eta} \right\}$$

OR

$$\theta^t := \arg \min_{\theta} \left\{ \langle \theta, \nabla \ell_{t-1}(\theta^{t-1}) \rangle + \frac{\|\theta - \theta^{t-1}\|^2}{2\eta} \right\}$$

## SVB

$$\mu^t = \arg \min_{\mu \in M} \left\{ \left\langle \mu, \nabla \mathbb{E}_{\theta \sim q_{\mu^{t-1}}} [\ell_{t-1}(\theta)] \right\rangle + \frac{D_\phi(q_\mu, q_{\mu^{t-1}})}{\eta} \right\}.$$

# SVA & SVB are tractable, and not equivalent

**Example :** Gaussian prior  $\theta \sim \pi = \mathcal{N}(0, s^2 I)$ ,  $D_\phi = \text{KL}$  and mean-field Gaussian approximation,  $\mu = (m, \sigma)$ .

$$\text{SVA} : m_{t+1} \leftarrow m_t - \eta s^2 \bar{g}_{m_t}, \quad g_{t+1} \leftarrow g_t + \bar{g}_{\sigma_t},$$

$$\sigma_{t+1} \leftarrow h(\eta s g_{t+1}) s,$$

$$\text{SVB} : m_{t+1} \leftarrow m_t - \eta \sigma_t^2 \bar{g}_{m_t},$$

$$\sigma_{t+1} \leftarrow \sigma_t h(\eta \sigma_t \bar{g}_{\sigma_t})$$

where  $h(x) := \sqrt{1+x^2} - x$  is applied componentwise, as well as the multiplication of two vectors, and

$$\bar{g}_{m_t} = \frac{\partial}{\partial m} \mathbb{E}_{\theta \sim \pi_{m_t, \sigma_t}} [\ell_t(\theta)],$$

$$\bar{g}_{\sigma_t} = \frac{\partial}{\partial \sigma} \mathbb{E}_{\theta \sim \pi_{m_t, \sigma_t}} [\ell_t(\theta)].$$

# Theoretical analysis of SVA

Two assumptions :

- ①  $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$  is  $L$ -Lipschitz and convex.

# Theoretical analysis of SVA

Two assumptions :

- ①  $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$  is  $L$ -Lipschitz and convex.

## Proposition

Assume  $\theta \mapsto \ell_t(\theta)$  is  $L/2$ -Lipschitz and convex, and  $\mu = (m, \Sigma)$  is a location scale parameter, then : satisfied.

# Theoretical analysis of SVA

Two assumptions :

- ①  $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$  is  $L$ -Lipschitz and convex.

## Proposition

Assume  $\theta \mapsto \ell_t(\theta)$  is  $L/2$ -Lipschitz and convex, and  $\mu = (m, \Sigma)$  is a location scale parameter, then : satisfied.

## Proof :



J. Domke (2019). *Provable smoothness guarantees for black-box variational inference*. NeurIPS.

# Theoretical analysis of SVA

Two assumptions :

- ①  $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$  is  $L$ -Lipschitz and convex.

## Proposition

Assume  $\theta \mapsto \ell_t(\theta)$  is  $L/2$ -Lipschitz and convex, and  $\mu = (m, \Sigma)$  is a location scale parameter, then : satisfied.

## Proof :



J. Domke (2019). *Provable smoothness guarantees for black-box variational inference*. NeurIPS.

- ②  $\mu \mapsto D_\phi(q_\mu, \pi)$  is  $\alpha$ -strongly convex.

# Theoretical analysis of SVA

Two assumptions :

- ①  $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)]$  is  $L$ -Lipschitz and convex.

## Proposition

Assume  $\theta \mapsto \ell_t(\theta)$  is  $L/2$ -Lipschitz and convex, and  $\mu = (m, \Sigma)$  is a location scale parameter, then : satisfied.

## Proof :



J. Domke (2019). *Provable smoothness guarantees for black-box variational inference*. NeurIPS.

- ②  $\mu \mapsto D_\phi(q_\mu, \pi)$  is  $\alpha$ -strongly convex.

For example true when  $q_\mu$  is Gaussian with  $\mu = (m, \Sigma)$  and  $D_\phi = \text{KL}$ .

# Theoretical analysis of SVA

## Theorem

Under the previous assumptions SVA leads to

$$\begin{aligned} & \sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \\ & \leq \inf_{\mu \in M} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)] + \frac{\eta L^2 T}{\alpha} + \frac{D_\phi(q_\mu, \pi)}{\eta} \right\}. \end{aligned}$$

# Theoretical analysis of SVA

## Theorem

Under the previous assumptions SVA leads to

$$\begin{aligned} & \sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \\ & \leq \inf_{\mu \in M} \left\{ \sum_{t=1}^T \mathbb{E}_{\theta \sim q_\mu} [\ell_t(\theta)] + \frac{\eta L^2 T}{\alpha} + \frac{D_\phi(q_\mu, \pi)}{\eta} \right\}. \end{aligned}$$

Application to Gaussian approximation with KL :

$$\sum_{t=1}^T \mathbb{E}_{\theta \sim q_{\mu_t}} [\ell_t(\theta)] \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + (1 + o(1))L\sqrt{dT \log(T)}.$$

# Theoretical analysis of SVB

## Theorem 2

Using Gaussian approximations and  $D_\phi = \text{KL}$ , assuming the loss is convex,  $L$ -Lipschitz and the parameter space bounded (diameter =  $D$ ), SVB with adequate  $\eta$  leads to

$$\sum_{t=1}^T \ell_t\left(\mathbb{E}_{\theta \sim q_{\mu_t}}(\theta)\right) \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + DL\sqrt{2T}.$$

# Theoretical analysis of SVB

## Theorem 2

Using Gaussian approximations and  $D_\phi = \text{KL}$ , assuming the loss is convex,  $L$ -Lipschitz and the parameter space bounded (diameter =  $D$ ), SVB with adequate  $\eta$  leads to

$$\sum_{t=1}^T \ell_t\left(\mathbb{E}_{\theta \sim q_{\mu_t}}(\theta)\right) \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + DL\sqrt{2T}.$$

If, moreover, the loss is  $H$ -strongly convex,

$$\sum_{t=1}^T \ell_t\left(\mathbb{E}_{\theta \sim q_{\mu_t}}(\theta)\right) \leq \inf_{\theta} \sum_{t=1}^T \ell_t(\theta) + \frac{L^2(1 + \log(T))}{H}.$$

## Test on a simulated dataset

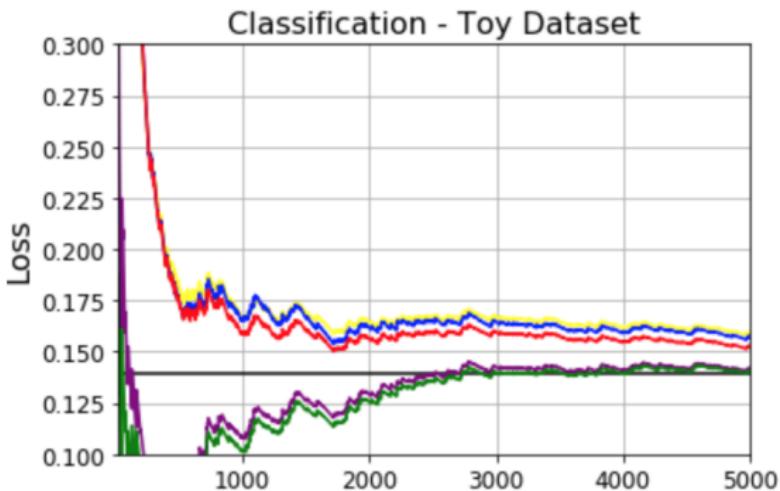
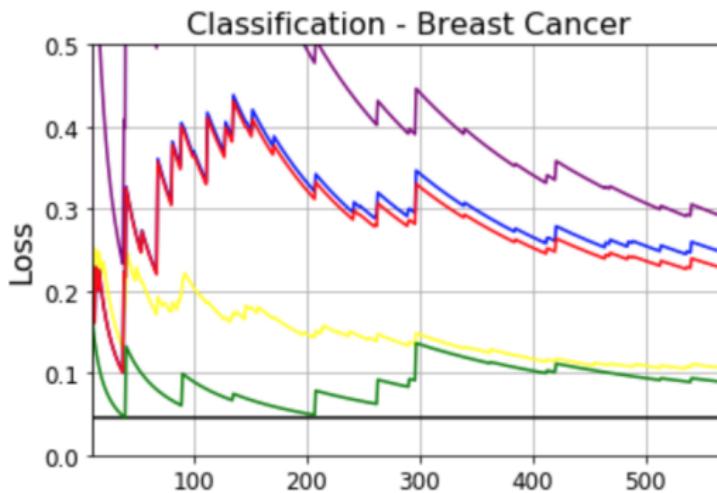


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

## Test on the Breast dataset



**Figure** – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

# Open questions

# Open questions

- ① Analysis of SVB in the general case.

# Open questions

- ① Analysis of SVB in the general case.
- ② Analysis of the uncertainty quantification.

# Open questions

- ① Analysis of SVB in the general case.
- ② Analysis of the uncertainty quantification.
- ③ NGVI is the next step in going closer to algorithms used to train Neural Networks with Bayesian principles. But being based on a different parametrization, it does not satisfy our convexity assumption...

# Open questions

- ① Analysis of SVB in the general case.
- ② Analysis of the uncertainty quantification.
- ③ NGVI is the next step in going closer to algorithms used to train Neural Networks with Bayesian principles. But being based on a different parametrization, it does not satisfy our convexity assumption...

Uses exponential family approximations  $\{q_\mu, \mu \in M\}$  where  $m$  is the mean parameter. Denoting  $\lambda$  the natural parameter (with  $\lambda = F(\mu)$ ),

$$\lambda^t = (1 - \rho)\lambda^{t-1} + \rho \nabla_\mu \mathbb{E}_{\theta \sim q_{\mu^{t-1}}} [\ell_t(\theta)],$$



M. E. Khan, D. Nielsen (2018). *Fast yet Simple Natural-Gradient Descent for Variational Inference in Complex Models*. ISITA.

Thank you !