

Generalization bounds for variational inference

Pierre Alquier



INSTITUT
POLYTECHNIQUE
DE PARIS

Elements de
maths. pour l'IA

école
normale
supérieure
paris—saclay

May 15, 2019

Notations

Assume that we observe X_1, \dots, X_n i.i.d from P_{θ_0} in a model $\{P_\theta, \theta \in \Theta\}$ dominated by $Q : \frac{dP_\theta}{dQ} = p_\theta$. Prior π on Θ .

Notations

Assume that we observe X_1, \dots, X_n i.i.d from P_{θ_0} in a model $\{P_\theta, \theta \in \Theta\}$ dominated by $Q : \frac{dP_\theta}{dQ} = p_\theta$. Prior π on Θ .

The likelihood

$$L_n(\theta) = \prod_{i=1}^n p_\theta(X_i)$$

Notations

Assume that we observe X_1, \dots, X_n i.i.d from P_{θ_0} in a model $\{P_{\theta}, \theta \in \Theta\}$ dominated by $Q : \frac{dP_{\theta}}{dQ} = p_{\theta}$. Prior π on Θ .

The likelihood

$$L_n(\theta) = \prod_{i=1}^n p_{\theta}(X_i)$$

The posterior

$$\pi_n(d\theta) \propto L_n(\theta)\pi(d\theta).$$

Notations

Assume that we observe X_1, \dots, X_n i.i.d from P_{θ_0} in a model $\{P_{\theta}, \theta \in \Theta\}$ dominated by $Q : \frac{dP_{\theta}}{dQ} = p_{\theta}$. Prior π on Θ .

The likelihood

$$L_n(\theta) = \prod_{i=1}^n p_{\theta}(X_i)$$

The posterior

$$\pi_n(d\theta) \propto L_n(\theta)\pi(d\theta).$$

The tempered posterior - $0 < \alpha < 1$

$$\pi_{n,\alpha}(d\theta) \propto [L_n(\theta)]^{\alpha}\pi(d\theta).$$

Computation of the posterior

- explicit form (conjugate models),

Computation of the posterior

- explicit form (conjugate models),
- MCMC algorithms : Metropolis-Hastings, Gibbs sampler, Langevin Monte Carlo...

Computation of the posterior

- explicit form (conjugate models),
- MCMC algorithms : Metropolis-Hastings, Gibbs sampler, Langevin Monte Carlo...

But...

- when the dimension is large, the convergence of MCMC can be extremely slow,

Computation of the posterior

- explicit form (conjugate models),
- MCMC algorithms : Metropolis-Hastings, Gibbs sampler, Langevin Monte Carlo...

But...

- when the dimension is large, the convergence of MCMC can be extremely slow,
- when the model is complex or when the sample size is large, each evaluation of $\pi_{n,\alpha}(\theta)$ can be expensive.

Computation of the posterior

- explicit form (conjugate models),
- MCMC algorithms : Metropolis-Hastings, Gibbs sampler, Langevin Monte Carlo...

But...

- when the dimension is large, the convergence of MCMC can be extremely slow,
- when the model is complex or when the sample size is large, each evaluation of $\pi_{n,\alpha}(\theta)$ can be expensive.

For these reasons, in the past 20 years, many methods targeting an approximation of $\pi_{n,\alpha}$ became popular : ABC, EP algorithm, **variational inference**, approximate MCMC ...

Variational approximations : definitions

Idea of VB : chose a family \mathcal{F} of probability distributions on Θ and approximate $\pi_{n,\alpha}$ by a distribution in \mathcal{F} :

Variational approximations : definitions

Idea of VB : chose a family \mathcal{F} of probability distributions on Θ and approximate $\pi_{n,\alpha}$ by a distribution in \mathcal{F} :

$$\tilde{\pi}_{n,\alpha} := \arg \min_{\rho \in \mathcal{F}} \mathcal{K}(\rho, \pi_{n,\alpha}).$$

Variational approximations : definitions

Idea of VB : chose a family \mathcal{F} of probability distributions on Θ and approximate $\pi_{n,\alpha}$ by a distribution in \mathcal{F} :

$$\tilde{\pi}_{n,\alpha} := \arg \min_{\rho \in \mathcal{F}} \mathcal{K}(\rho, \pi_{n,\alpha}).$$

Examples :

- parametric approximation

$$\mathcal{F} = \{ \mathcal{N}(\mu, \Sigma) : \mu \in \mathbb{R}^d, \Sigma \in \mathcal{S}_d^+ \}.$$

Variational approximations : definitions

Idea of VB : chose a family \mathcal{F} of probability distributions on Θ and approximate $\pi_{n,\alpha}$ by a distribution in \mathcal{F} :

$$\tilde{\pi}_{n,\alpha} := \arg \min_{\rho \in \mathcal{F}} \mathcal{K}(\rho, \pi_{n,\alpha}).$$

Examples :

- parametric approximation

$$\mathcal{F} = \{ \mathcal{N}(\mu, \Sigma) : \mu \in \mathbb{R}^d, \Sigma \in \mathcal{S}_d^+ \}.$$

- mean-field approximation, $\Theta = \Theta_1 \times \Theta_2$ and

$$\mathcal{F} : \{ \rho : \rho(d\theta) = \rho_1(d\theta_1) \times \rho_2(d\theta_2) \}.$$

Empirical lower bound (ELBO)

Note that :

$$\begin{aligned}\tilde{\pi}_{n,\alpha} &= \arg \min_{\rho \in \mathcal{F}} \mathcal{K}(\rho, \pi_{n,\alpha}) \\ &= \arg \min_{\rho \in \mathcal{F}} \underbrace{\left\{ -\alpha \int \frac{1}{n} \sum_{i=1}^n \log p_{\theta}(X_i) \rho(d\theta) + \mathcal{K}(\rho, \pi) \right\}}_{-\text{ELBO}(\rho)}.\end{aligned}$$

Empirical lower bound (ELBO)

Note that :

$$\begin{aligned}\tilde{\pi}_{n,\alpha} &= \arg \min_{\rho \in \mathcal{F}} \mathcal{K}(\rho, \pi_{n,\alpha}) \\ &= \arg \min_{\rho \in \mathcal{F}} \underbrace{\left\{ -\alpha \int \frac{1}{n} \sum_{i=1}^n \log p_{\theta}(X_i) \rho(d\theta) + \mathcal{K}(\rho, \pi) \right\}}_{-\text{ELBO}(\rho)}.\end{aligned}$$

So we have the equivalent definition :

$$\tilde{\pi}_{n,\alpha} := \arg \max_{\rho \in \mathcal{F}} \text{ELBO}(\rho).$$

Outline of the talk

After this introduction :

Outline of the talk

After this introduction :

Section 2 will address the following question :

What are the conditions ensuring that $\tilde{\pi}_{n,\alpha}$ leads to good estimators ?

Outline of the talk

After this introduction :

Section 2 will address the following question :

What are the conditions ensuring that $\tilde{\pi}_{n,\alpha}$ leads to good estimators ?

We will show general conditions, and many examples.

Outline of the talk

After this introduction :

Section 2 will address the following question :

What are the conditions ensuring that $\tilde{\pi}_{n,\alpha}$ leads to good estimators ?

We will show general conditions, and many examples.

Section 3 will address the following question :

Are there efficient algorithms to (provably) compute $\tilde{\pi}_{n,\alpha}$?

Outline of the talk

After this introduction :

Section 2 will address the following question :

What are the conditions ensuring that $\tilde{\pi}_{n,\alpha}$ leads to good estimators ?

We will show general conditions, and many examples.

Section 3 will address the following question :

Are there efficient algorithms to (provably) compute $\tilde{\pi}_{n,\alpha}$?

We will see that fast algorithms from sequential optimization can be used in some cases. This also allows to do variational inference on a data stream that cannot be stored.

Outline of the talk

- 1 Introduction : variational Bayesian inference
 - Bayesian inference
 - Definition of variational approximations
 - Outline of the talk
- 2 Concentration of variational approximations of the posterior
 - Theoretical results
 - Applications
- 3 Online variational inference
 - Sequential estimation problem
 - Online variational inference
 - Simulations

Tools for the consistency of VB

The α -Rényi divergence for $\alpha \in (0, 1)$

$$D_{\alpha}(P, R) = \frac{1}{\alpha - 1} \log \int (\mathrm{d}P)^{\alpha} (\mathrm{d}R)^{1-\alpha}.$$

Tools for the consistency of VB

The α -Rényi divergence for $\alpha \in (0, 1)$

$$D_\alpha(P, R) = \frac{1}{\alpha - 1} \log \int (\mathrm{d}P)^\alpha (\mathrm{d}R)^{1-\alpha}.$$

All the properties derived in :



T. Van Erven & P. Harremos. Rényi divergence and Kullback-Leibler divergence. *IEEE Transactions on Information Theory*, 2014.

Among others, for $1/2 \leq \alpha$, link with Hellinger and Kullback :

$$\mathcal{H}^2(P, R) \leq D_\alpha(P, R) \xrightarrow[\alpha \nearrow 1]{} \mathcal{K}(P, R).$$

What do we know about $\pi_{n,\alpha}$?

$$\mathcal{B}(r) = \{\theta \in \Theta : \mathcal{K}(P_{\theta_0}, P_\theta) \leq r\}.$$

Theorem, variant of (Bhattacharya, Pati & Yang)

For any sequence (r_n) such that

$$-\log \pi[B(r_n)] \leq nr_n$$

we have

$$\mathbb{E} \left[\int D_\alpha(P_\theta, P_{\theta_0}) \pi_{n,\alpha}(\mathrm{d}\theta) \right] \leq \frac{1+\alpha}{1-\alpha} r_n.$$



A. Bhattacharya, D. Pati & Y. Yang. Bayesian fractional posteriors. *The Annals of Statistics*, 2019.

Extension of previous result to VB

Theorem (A. & Ridgway)

If there is $\rho_n \in \mathcal{F}$ and (r_n) such that

$$\begin{cases} \int \mathcal{K}(P_{\theta_0}, P_{\theta}) \rho_n(d\theta) \leq r_n, \\ \text{and} \\ \mathcal{K}(\rho_n, \pi) \leq nr_n, \end{cases}$$

then, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{1 + \alpha}{1 - \alpha} r_n.$$

Extension of previous result to VB

Theorem (A. & Ridgway)

If there is $\rho_n \in \mathcal{F}$ and (r_n) such that

$$\begin{cases} \int \mathcal{K}(P_{\theta_0}, P_{\theta}) \rho_n(d\theta) \leq r_n, \\ \text{and} \\ \mathcal{K}(\rho_n, \pi) \leq nr_n, \end{cases}$$

then, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_{\alpha}(P_{\theta}, P_{\theta_0}) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{1+\alpha}{1-\alpha} r_n.$$



P. Alquier & J. Ridgway. Concentration of tempered posteriors and of their variational approximations. *The Annals of Statistics*, to appear.

Misspecified case

Assume now that X_1, \dots, X_n i.i.d $\sim Q \notin \{P_\theta, \theta \in \Theta\}$. Put :

$$\theta^* := \arg \min_{\theta \in \Theta} \mathcal{K}(Q, P_\theta).$$

Theorem (A. and Ridgway)

Assume that there is $\rho_n \in \mathcal{F}$ such that

$$\int \mathbb{E} \left[\log \frac{dP_{\theta^*}}{dP_\theta} \right] \rho_n(d\theta) \leq r_n \text{ and } \mathcal{K}(\rho_n, \pi) \leq nr_n,$$

then, for any $\alpha \in (0, 1)$,

$$\mathbb{E} \left[\int D_\alpha(P_\theta, Q) \tilde{\pi}_{n,\alpha}(d\theta) \right] \leq \frac{\alpha}{1-\alpha} \mathcal{K}(Q, P_{\theta^*}) + \frac{1+\alpha}{1-\alpha} r_n.$$

First example : nonparametric regression

Nonparametric regression

- $Y_i = f(X_i) + \xi_i,$

First example : nonparametric regression

Nonparametric regression

- $Y_i = f(X_i) + \xi_i,$
- $\xi_i \sim \mathcal{N}(0, \sigma^2),$

First example : nonparametric regression

Nonparametric regression

- $Y_i = f(X_i) + \xi_i$,
- $\xi_i \sim \mathcal{N}(0, \sigma^2)$,
- f is s -smooth with s unknown,

First example : nonparametric regression

Nonparametric regression

- $Y_i = f(X_i) + \xi_i$,
- $\xi_i \sim \mathcal{N}(0, \sigma^2)$,
- f is s -smooth with s unknown,
- prior : $f(\cdot) = \sum_{j=1}^K \beta_j \phi_j(\cdot)$, random K and β_j 's, (ϕ_j) basis...

First example : nonparametric regression

Nonparametric regression

- $Y_i = f(X_i) + \xi_i$,
- $\xi_i \sim \mathcal{N}(0, \sigma^2)$,
- f is s -smooth with s unknown,
- prior : $f(\cdot) = \sum_{j=1}^K \beta_j \phi_j(\cdot)$, random K and β_j 's, (ϕ_j) basis...
- variational approx : β_j mutually independent...

Under suitable assumptions, $r_n \sim \left(\frac{\log(n)}{n} \right)^{\frac{2s}{2s+1}}$.

More examples covered in the paper

- 1 logistic regression,




More examples covered in the paper

- 1 logistic regression,
- 2 matrix completion : we prove that the approx. in



Y. J. Lim & Y. W. Teh. Variational Bayesian approach to movie rating prediction. *Proceedings of KDD cup and workshop*, 2007.

leads to minimax-optimal estimation.

				
Claire	4	?	3	...
Nial	?	4	?	...
Brendon	?	5	4	...
Andrew	?	4	?	...
Adrian	1	?	?	...
Damien	?	1	?	...
⋮	⋮	⋮	⋮	⋮

Extensions

- 1 case $\alpha = 1$, i.e approximation of the “usual” posterior :



F. Zhang & C. Gao. Convergence Rates of Variational Posterior Distributions. *Preprint arXiv*, 2017.

Extensions

- 1 case $\alpha = 1$, i.e approximation of the “usual” posterior :



F. Zhang & C. Gao. Convergence Rates of Variational Posterior Distributions. *Preprint arXiv*, 2017.

- 2 approximation based on another distance, for example :

$$\tilde{\pi}_{n,\alpha} := \arg \min_{\rho \in \mathcal{F}} \mathcal{W}(\rho, \pi_{n,\alpha}) \text{ (Wasserstein distance),}$$

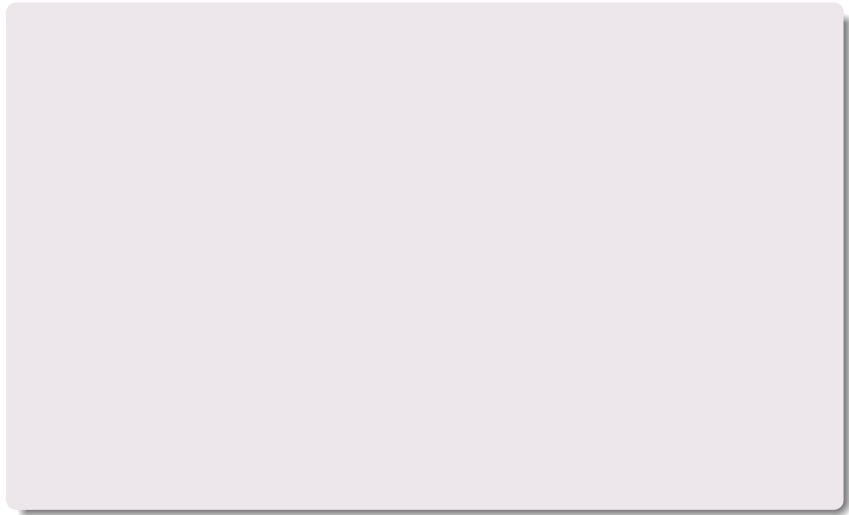


J. Huggins, T. Campbell, M. Kasprzak & T. Broderick. Practical bounds on the error of Bayesian posterior approximations : a nonasymptotic approach. *Preprint arXiv*, 2018.

Outline of the talk

- 1 Introduction : variational Bayesian inference
 - Bayesian inference
 - Definition of variational approximations
 - Outline of the talk
- 2 Concentration of variational approximations of the posterior
 - Theoretical results
 - Applications
- 3 Online variational inference
 - Sequential estimation problem
 - Online variational inference
 - Simulations

Sequential estimation problem



Sequential estimation problem

- 1 initialize θ_1 ,

Sequential estimation problem

- 1 initialize θ_1 ,
- 2 x_1 revealed,

Sequential estimation problem

- 1
- 1 initialize θ_1 ,
- 2 x_1 revealed,
- 3 incur loss
– $\log p_{\theta_1}(x_1)$

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,
 - 2 x_3 revealed,

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,
 - 2 x_3 revealed,
 - 3 incur loss
 $-\log p_{\theta_3}(x_3)$
- 4 ...

Sequential estimation problem

Objective :

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,
 - 2 x_3 revealed,
 - 3 incur loss
 $-\log p_{\theta_3}(x_3)$
- 4 ...

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,
 - 2 x_3 revealed,
 - 3 incur loss
 $-\log p_{\theta_3}(x_3)$

4 ...

Objective : make sure that
we learn to predict well as **fast**
as **possible**.

Sequential estimation problem

- 1
 - 1 initialize θ_1 ,
 - 2 x_1 revealed,
 - 3 incur loss
 $-\log p_{\theta_1}(x_1)$
- 2
 - 1 update $\theta_1 \rightarrow \theta_2$,
 - 2 x_2 revealed,
 - 3 incur loss
 $-\log p_{\theta_2}(x_2)$
- 3
 - 1 update $\theta_2 \rightarrow \theta_3$,
 - 2 x_3 revealed,
 - 3 incur loss
 $-\log p_{\theta_3}(x_3)$

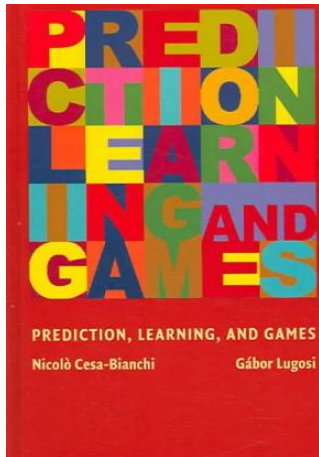
4 ...

Objective : make sure that we learn to predict well as **fast as possible**. Keep

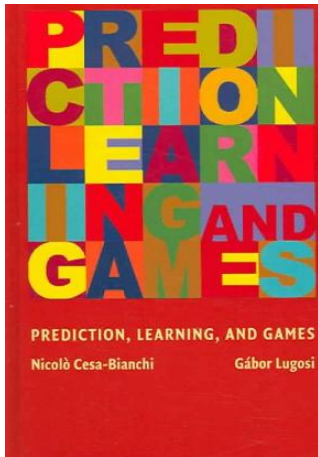
$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)]$$

as small as possible for any T ,
without stochastic assumptions on the data.

Reference



Reference



The regret :

$$R(T) = \sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \\ - \inf_{\theta \in \Theta} \sum_{t=1}^T [-\log p_{\theta}(x_t)].$$

EWA strategy / multiplicative update...

EWA strategy / multiplicative update...

- learning rate $\alpha > 0$.

EWA strategy / multiplicative update...

- learning rate $\alpha > 0$.
- initialize $p_1 = \pi$ (the prior).

EWA strategy / multiplicative update...

- learning rate $\alpha > 0$.
- initialize $p_1 = \pi$ (the prior).

Algorithm 2 Exponentially Weighted Aggregation

- 1: **for** $t = 1, 2, \dots$ **do**
 - 2: $\theta_t = \mathbb{E}_{\theta \sim p_t}[\theta]$,
 - 3: x_t revealed, update $p_{t+1}(d\theta) = \frac{[p_{\theta}(x_t)]^{\alpha} p_t(d\theta)}{\int [p_{\vartheta}(x_t)]^{\alpha} p_t(d\vartheta)}$.
 - 4: **end for**
-

EWA strategy / multiplicative update...

- learning rate $\alpha > 0$.
- initialize $p_1 = \pi$ (the prior).

Algorithm 2 Exponentially Weighted Aggregation

- 1: **for** $t = 1, 2, \dots$ **do**
 - 2: $\theta_t = \mathbb{E}_{\theta \sim p_t}[\theta]$,
 - 3: x_t revealed, update $p_{t+1}(d\theta) = \frac{[p_\theta(x_t)]^\alpha p_t(d\theta)}{\int [p_{\vartheta}(x_t)]^\alpha p_t(d\vartheta)}$.
 - 4: **end for**
-

Note that $p_t = \pi_{n,\alpha}$ the tempered posterior, so problem : how can we compute θ_t ?

A regret bound for EWA

From now, $\theta \mapsto [-\log p_\theta(x_t)]$ is convex + bounded : $|\cdot| \leq C$.

A regret bound for EWA

From now, $\theta \mapsto [-\log p_\theta(x_t)]$ is convex + bounded : $|\cdot| \leq C$.

Theorem

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_p \left[\sum_{t=1}^T \mathbb{E}_{\theta \sim p} [-\log p_\theta(x_t)] + \frac{\alpha C^2 T}{2} + \frac{\mathcal{K}(p, \pi)}{\alpha} \right].$$

A regret bound for EWA

From now, $\theta \mapsto [-\log p_\theta(x_t)]$ is convex + bounded : $|\cdot| \leq C$.

Theorem

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_p \left[\sum_{t=1}^T \mathbb{E}_{\theta \sim p} [-\log p_\theta(x_t)] + \frac{\alpha C^2 T}{2} + \frac{\mathcal{K}(p, \pi)}{\alpha} \right].$$

Under similar assumptions than in the batch case, that is, the prior gives enough mass to relevant θ , and $\alpha \sim 1/\sqrt{T}$,

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_{\theta \in \Theta} \sum_{t=1}^T [-\log p_\theta(x_t)] + \text{cst.} \sqrt{T}$$

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_{\theta \in \Theta} \sum_{t=1}^T [-\log p_{\theta}(x_t)] + \text{cst.} \sqrt{T}$$

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_{\theta \in \Theta} \sum_{t=1}^T [-\log p_{\theta}(x_t)] + \text{cst.} \sqrt{T}$$

$$\frac{1}{T} \sum_{t=1}^T \log \frac{q(x_t)}{p_{\theta_t}(x_t)} \leq \inf_{\theta \in \Theta} \frac{1}{T} \sum_{t=1}^T \log \frac{q(x_t)}{p_{\theta}(x_t)} + \frac{\text{cst}}{\sqrt{T}}.$$

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \leq \inf_{\theta \in \Theta} \sum_{t=1}^T [-\log p_{\theta}(x_t)] + \text{cst} \cdot \sqrt{T}$$

$$\frac{1}{T} \sum_{t=1}^T \log \frac{q(x_t)}{p_{\theta_t}(x_t)} \leq \inf_{\theta \in \Theta} \frac{1}{T} \sum_{t=1}^T \log \frac{q(x_t)}{p_{\theta}(x_t)} + \frac{\text{cst}}{\sqrt{T}}.$$

Assuming that x_1, \dots, x_T are actually i.i.d from Q , with density q , define

$$\hat{\theta}_T = \frac{1}{T} \sum_{t=1}^T \theta_t,$$

we have (“online-to-batch” conversion) :

$$\mathbb{E} [\mathcal{K}(Q, P_{\hat{\theta}_T})] \leq \inf_{\theta \in \Theta} \mathcal{K}(Q, P_{\theta}) + \frac{\text{cst}}{\sqrt{T}}.$$

Variational approximations of EWA



B.-E. Chérif-Abdellatif, P. Alquier & M. E. Khan. A Generalization Bound for Online Variational Inference. *Preprint arXiv*, 2019.

Variational approximations of EWA



B.-E. Chérif-Abdellatif, P. Alquier & M. E. Khan. A Generalization Bound for Online Variational Inference. *Preprint arXiv*, 2019.



Variational approximations of EWA



B.-E. Chérif-Abdellatif, P. Alquier & M. E. Khan. A Generalization Bound for Online Variational Inference. *Preprint arXiv*, 2019.



Parametric variational approximation : $\mathcal{F} = \{q_\mu, \mu \in M\}$.

Objective : propose a way to update $\mu_t \rightarrow \mu_{t+1}$ so that q_{μ_t} leads to similar performances as p_t in EWA...

SVA and SVB strategies

Algorithm 3 SVA (Sequential Variational Approximation)

- 1: **for** $t = 1, 2, \dots$ **do**
- 2: $\theta_t = \mathbb{E}_{\theta \sim q_{\mu_t}}[\theta],$
- 3: x_t revealed, update

$$\mu_{t+1} = \arg \min_{\mu \in M} \left[\mu^T \nabla_{\mu} \sum_{i=1}^t \mathbb{E}_{\theta \sim q_{\mu}} [-\log p_{\theta}(x_i)] + \frac{\mathcal{K}(q_{\mu}, \pi)}{\alpha} \right].$$

- 4: **end for**
-

SVA and SVB strategies

Algorithm 3 SVA (Sequential Variational Approximation)

- 1: **for** $t = 1, 2, \dots$ **do**
- 2: $\theta_t = \mathbb{E}_{\theta \sim q_{\mu_t}}[\theta],$
- 3: x_t revealed, update

$$\mu_{t+1} = \arg \min_{\mu \in M} \left[\mu^T \nabla_{\mu} \sum_{i=1}^t \mathbb{E}_{\theta \sim q_{\mu}} [-\log p_{\theta}(x_i)] + \frac{\mathcal{K}(q_{\mu}, \pi)}{\alpha} \right].$$

- 4: **end for**
-

SVB (Streaming Variational Bayes) has update

$$\mu_{t+1} = \arg \min_{\mu \in M} \left[\mu^T \nabla_{\mu} \mathbb{E}_{\theta \sim q_{\mu}} [-\log p_{\theta}(x_t)] + \frac{\mathcal{K}(q_{\mu}, q_{\mu_t})}{\alpha} \right].$$

NGVI strategy

NGVI (Natural Gradient Variational Inference) : fix some $\beta > 0$,

$$\begin{aligned} & \mu_{t+1} \\ &= \arg \min_{\mu \in M} \left[\mu^T \nabla_{\mu} \mathbb{E}_{\theta \sim q_{\mu}} [-\log p_{\theta}(x_t)] + \frac{\mathcal{K}(q_{\mu}, \pi)}{\alpha} + \frac{\mathcal{K}(q_{\mu}, q_{\mu_t})}{\beta} \right]. \end{aligned}$$

NGVI strategy

NGVI (Natural Gradient Variational Inference) : fix some $\beta > 0$,

$$\mu_{t+1} = \arg \min_{\mu \in M} \left[\mu^T \nabla_{\mu} \mathbb{E}_{\theta \sim q_{\mu}} [-\log p_{\theta}(x_t)] + \frac{\mathcal{K}(q_{\mu}, \pi)}{\alpha} + \frac{\mathcal{K}(q_{\mu}, q_{\mu_t})}{\beta} \right].$$



M. E. Khan & W. Lin. Conjugate-computation variational inference : Converting variational inference in non-conjugate models to inferences in conjugate models. *AISTAT*, 2017.

An example : SVB with Gaussian approximations

As an example, assume that $\theta \in \mathbb{R}^d$, the prior is

$\pi = \mathcal{N}(0, s^2 I)$ and that we use the variational approximation

$$\text{family : } q_\mu = q_{m,\sigma} = \mathcal{N} \left(m, \begin{pmatrix} \sigma_1^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_d^2 \end{pmatrix} \right).$$

An example : SVB with Gaussian approximations

As an example, assume that $\theta \in \mathbb{R}^d$, the prior is $\pi = \mathcal{N}(0, s^2 I)$ and that we use the variational approximation

$$\text{family : } q_{\mu} = q_{m, \sigma} = \mathcal{N} \left(m, \begin{pmatrix} \sigma_1^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_d^2 \end{pmatrix} \right).$$

In this case, the update in SVB is :

$$m_{t+1} = m_t - \alpha \sigma_t^2 \odot \nabla_{m=m_t} \mathbb{E}_{\theta \sim q_{m, \sigma_t}} [-\log p_{\theta}(x_t)]$$

$$\sigma_{t+1} = \sigma_t \odot h \left(\frac{\alpha \sigma_t \nabla_{\sigma=\sigma_t} \mathbb{E}_{\theta \sim q_{m_t, \sigma}} [-\log p_{\theta}(x_t)]}{2} \right)$$

where \odot means “componentwise multiplication” and $h(x) = \sqrt{1 + x^2} - x$ is also applied componentwise.

An example : SVB with Gaussian approximations

As an example, assume that $\theta \in \mathbb{R}^d$, the prior is $\pi = \mathcal{N}(0, s^2 I)$ and that we use the variational approximation

$$\text{family : } q_\mu = q_{m,\sigma} = \mathcal{N} \left(m, \begin{pmatrix} \sigma_1^2 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_d^2 \end{pmatrix} \right).$$

In this case, the update in SVB is :

$$m_{t+1} = m_t - \alpha \sigma_t^2 \odot \nabla_{m=m_t} \mathbb{E}_{\theta \sim q_{m,\sigma_t}} [-\log p_\theta(x_t)]$$

$$\sigma_{t+1} = \sigma_t \odot h \left(\frac{\alpha \sigma_t \nabla_{\sigma=\sigma_t} \mathbb{E}_{\theta \sim q_{m_t,\sigma}} [-\log p_\theta(x_t)]}{2} \right)$$

where \odot means “componentwise multiplication” and $h(x) = \sqrt{1+x^2} - x$ is also applied componentwise. We also have explicit formulas for SVA and NGVI (see the paper).

A regret bound for SVA

Theorem (Chérif-Abdellatif, A. & Khan)

Assume that $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [-\log p_\theta(x_t)]$ is L -Lipschitz and convex.

A regret bound for SVA

Theorem (Chérif-Abdellatif, A. & Khan)

Assume that $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [-\log p_\theta(x_t)]$ is L -Lipschitz and convex. (this is for example the case as soon as the log-likelihood is concave in θ and L -Lipschitz, and μ is a location-scale parameter).

A regret bound for SVA

Theorem (Chérif-Abdellatif, A. & Khan)

Assume that $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [-\log p_\theta(x_t)]$ is L -Lipschitz and convex. Assume that $\mu \mapsto \mathcal{K}(p_\mu, \pi)$ is γ -strongly convex. Then SVA satisfies :

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \\ \leq \inf_{\mu \in M} \left\{ \mathbb{E}_{\theta \sim q_\mu} \left[\sum_{t=1}^T [-\log p_\theta(x_t)] \right] + \frac{\alpha L^2 T}{\gamma} + \frac{\mathcal{K}(q_\mu, \pi)}{\alpha} \right\}.$$

A regret bound for SVA

Theorem (Chérif-Abdellatif, A. & Khan)

Assume that $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [-\log p_\theta(x_t)]$ is L -Lipschitz and convex. Assume that $\mu \mapsto \mathcal{K}(p_\mu, \pi)$ is γ -strongly convex. Then SVA satisfies :

$$\sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \\ \leq \inf_{\mu \in M} \left\{ \mathbb{E}_{\theta \sim q_\mu} \left[\sum_{t=1}^T [-\log p_\theta(x_t)] \right] + \frac{\alpha L^2 T}{\gamma} + \frac{\mathcal{K}(q_\mu, \pi)}{\alpha} \right\}.$$

For SVB : some results in the Gaussian case.

A regret bound for SVA

Theorem (Chérif-Abdellatif, A. & Khan)

Assume that $\mu \mapsto \mathbb{E}_{\theta \sim q_\mu} [-\log p_\theta(x_t)]$ is L -Lipschitz and convex. Assume that $\mu \mapsto \mathcal{K}(p_\mu, \pi)$ is γ -strongly convex. Then SVA satisfies :

$$\begin{aligned} & \sum_{t=1}^T [-\log p_{\theta_t}(x_t)] \\ & \leq \inf_{\mu \in M} \left\{ \mathbb{E}_{\theta \sim q_\mu} \left[\sum_{t=1}^T [-\log p_\theta(x_t)] \right] + \frac{\alpha L^2 T}{\gamma} + \frac{\mathcal{K}(q_\mu, \pi)}{\alpha} \right\}. \end{aligned}$$

For SVB : some results in the Gaussian case. For NGVI : we were not able to derive regret bounds until now.

Test on a simulated dataset

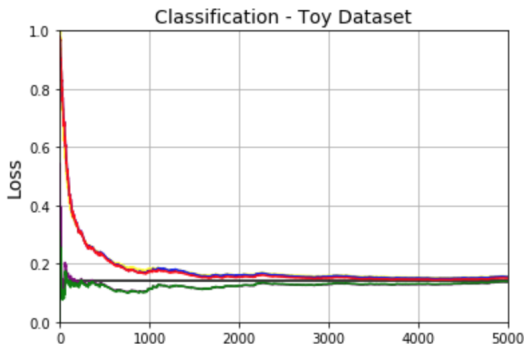


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Breast dataset

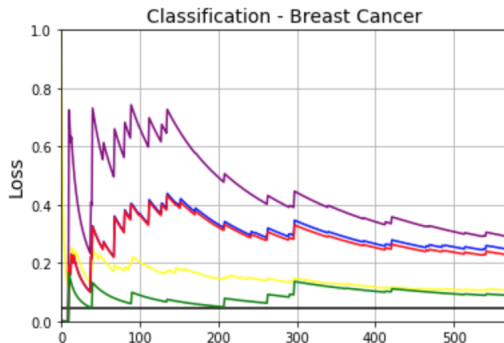


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Pima Indians dataset

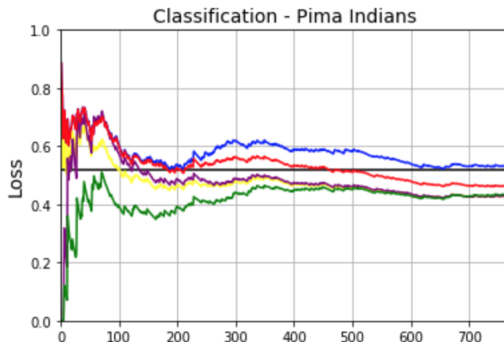


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Boston Housing dataset

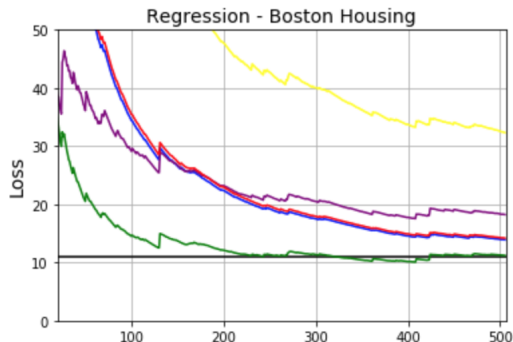


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Test on the Forest Cover Type dataset

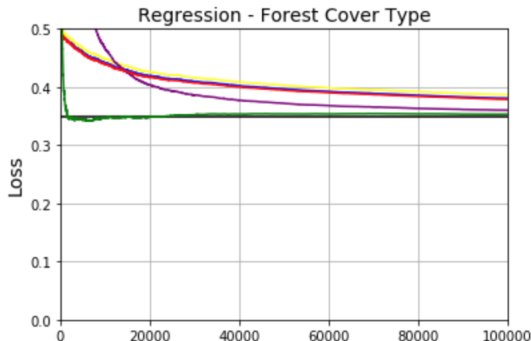


Figure – Average cumulative losses on different datasets for classification and regression tasks with OGA (yellow), OGA-EL (red), SVA (blue), SVB (purple) and NGVI (green).

Conclusions

- 1 Using online-to-batch conversion, we now have algorithms for variational inference with provable statistical properties after a finite number of steps.

Conclusions

- 1 Using online-to-batch conversion, we now have algorithms for variational inference with provable statistical properties after a finite number of steps.
- 2 SVA, SVB competitive with OGA (online gradient algorithm, “non-Bayesian”).

Conclusions

- ➊ Using online-to-batch conversion, we now have algorithms for variational inference with provable statistical properties after a finite number of steps.
- ➋ SVA, SVB competitive with OGA (online gradient algorithm, “non-Bayesian”).
- ➌ NGVI is the best method on all datasets. Its theoretical analysis is thus an important open problem. Cannot be done with our current techniques (using natural parameters in exponential models lead to non-convex objectives).

Thank you !