

# MMD-Bayes

Robust Bayesian Estimation via Maximum Mean Discrepancy

Pierre Alquier



Center for  
Advanced Intelligence Project

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Approximate Bayesian  
Inference team (ABI), lead  
by Emtiyaz Khan



Please visit the team website

<https://emtiyaz.github.io/>



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One of the recurring idea in the team's work :

$$\pi(\theta|X) \propto \underbrace{\pi(X|\theta)}_{\text{likelihood}} \underbrace{\pi(\theta)}_{\text{prior}} \rightarrow \pi(\theta|X) \propto \underbrace{\exp(-\alpha L(X, \theta))}_{\text{loss function}} \underbrace{\pi(\theta)}_{\text{prior}}.$$



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P. Alquier, N. Chopin and J. Ridgway (2016). On the Properties of Variational Approximations of Gibbs Posteriors. *Journal of Machine Learning Research*.



K. Osawa, S. Swaroop, A. Jain, R. Eschenhagen, R. E. Turner, R. Yokota, M. E. Khan (2019). Practical Deep Learning with Bayesian Principles. *NeurIPS*.



Today : a loss  
function leading to  
**robust estimation.**

Joint works with :

Badr-Eddine  
Chérif-Abdellatif.



B.-E. Chérif-Abdellatif, P. Alquier (2019). MMD-Bayes : Robust Bayesian Estimation via Maximum Mean Discrepancy. AABI 2019.



B.-E. Chérif-Abdellatif, P. Alquier (2019). Finite Sample Properties of Parametric MMD Estimation : Robustness to Misspecification and Dependence. Preprint arxiv :1912.05737.

- 1 Introduction : some problems with the likelihood
- 2 Kernels and MMD distance
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# The Maximum Likelihood Estimator (MLE)

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Statistical inference :

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Letting  $p_\theta$  denote the density of  $P_\theta$ , then

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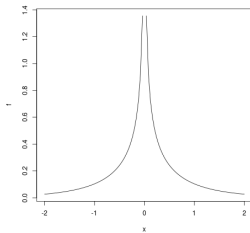
Example :  $P_{(m,\sigma)} = \mathcal{N}(m, \sigma^2)$  then

$$\hat{m} = \frac{1}{n} \sum_{i=1}^n X_i \text{ and } \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \hat{m})^2.$$

# MLE not unique / not consistent

Example :

$$p_{\theta}(x) = \frac{\exp(-|x - \theta|)}{2\sqrt{\pi}|x - \theta|},$$

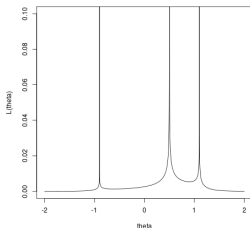
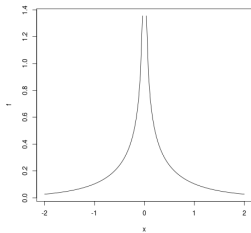


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$$L(\theta) = \frac{\exp(-\sum_{i=1}^n |X_i - \theta|)}{(2\sqrt{\pi})^n \prod_{i=1}^n \sqrt{|X_i - \theta|}}.$$



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Huber proposed the **contamination** model : with probability  $\varepsilon$ ,  $X_i$  is not drawn from  $P_{\theta_0}$  but from  $Q$  that can be **anything** :

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In the case of the following contamination, the MLE is extremely far from the truth :

$$P_0 = (1 - \varepsilon).\text{Unif}[0, 1] + \varepsilon.\mathcal{N}(10034, 1)...$$

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The MLE does not satisfy these requirements.

## Some examples

Yatracos' skeleton estimate  $\hat{\theta}_n^Y$  :

$$\mathbb{E} \left[ d_{TV}(P_{\hat{\theta}_n^Y}, P_0) \right] \leq 3d_{TV}(P_0, P_{\theta_0}) + C \cdot \sqrt{\frac{\dim(\Theta)}{n}}$$

where

$$d_{TV}(P, Q) = \sup_E |P(E) - Q(E)|.$$



Yatracos, Y. G. (1985). Rates of convergence of minimum distance estimators and Kolmogorov's entropy. *Annals of Statistics*.

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More recent work with the Hellinger distance :



Baraud, Y., Birgé, L., & Sart, M. (2017). A new method for estimation and model selection :  $\rho$ -estimation. *Inventiones mathematicae*.

But...



# But...

Problem with the aforementioned estimators : they cannot be computed in practice.

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Additional requirement : an estimator must be computable!!!

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## Reminder : kernels

Let  $\mathcal{H}$  be a Hilbert space and any continuous function  $\Phi : \mathcal{X} \rightarrow \mathcal{H}$ . The function

$$K(x, y) = \langle \Phi(x), \Phi(y) \rangle_{\mathcal{H}}$$

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is called a **kernel**. Conversely :

### Mercer's theorem

Let  $K(x, y)$  be a continuous function such that for any  $(x_1, \dots, x_n) \in \mathcal{X}^n$  and  $(c_1, \dots, c_n) \neq (0, \dots, 0) \in \mathbb{R}^n$ ,

$$\sum_{i=1}^n \sum_{j=1}^n c_i c_j K(x_i, x_j) > 0,$$

then there is  $\mathcal{H}$  and  $\Phi$  such that  $K(x, y) = \langle \Phi(x), \Phi(y) \rangle_{\mathcal{H}}$ .

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Assume that the kernel is bounded :  $0 \leq K(x, y) \leq 1$ .

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### Definition : the MMD distance

$$\mathbb{D}_K(P, Q) = \|\mu_K(P) - \mu_K(Q)\|_{\mathcal{H}}.$$

# MMD-based estimator

Reminder of the context :  $X_1, \dots, X_n$  be i.i.d in  $\mathcal{X}$  from a probability distribution  $P_0$ , model  $(P_\theta, \theta \in \Theta)$ .

## Definition - MMD based estimator

$$\hat{\theta}_n^{MMD} = \arg \min_{\theta \in \Theta} \mathbb{D}_K(P_\theta, \hat{P}_n) \quad \text{where } \hat{P}_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}.$$

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Even though this idea was sometimes used before, the first theoretical study :



Briol, F. X., Barp, A., Duncan, A. B., & Girolami, M. (2019). Statistical Inference for Generative Models with Maximum Mean Discrepancy. *Preprint arXiv :1906.05944*.

# Universal estimation with MMD

## Theorem - Chérif-Abdellatif + PA

For any  $P_0$ , when  $X_1, \dots, X_n$  are i.i.d from  $P_0$ ,

$$\mathbb{E} \left[ \mathbb{D}_K \left( P_{\hat{\theta}_n^{MMD}}, P_0 \right) \right] \leq \inf_{\theta \in \Theta} \mathbb{D}_K(P_\theta, P_0) + \frac{2}{\sqrt{n}}.$$

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## Corollary - Huber contamination model

When  $X_1, \dots, X_n$  are i.i.d from  $(1 - \varepsilon)P_{\theta_0} + \varepsilon Q$ ,

$$\mathbb{E} \left[ \mathbb{D}_K \left( P_{\hat{\theta}_n^{MMD}}, P_0 \right) \right] \leq 2\varepsilon + \frac{2}{\sqrt{n}}.$$

# How to compute $\hat{\theta}_n^{MMD}$ ?

We actually have

$$\mathbb{D}_K^2(P_\theta, \hat{P}_n) = \mathbb{E}_{X, X' \sim P_\theta} [K(X, X')] - \frac{2}{n} \sum_{i=1}^n \mathbb{E}_{X \sim P_\theta} [K(X_i, X)] + \frac{1}{n^2} \sum_{1 \leq i, j \leq n} K(X_i, X_j)$$

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and so

$$\begin{aligned} & \nabla_\theta \mathbb{D}_K^2(P_\theta, \hat{P}_n) \\ &= 2 \mathbb{E}_{X, X' \sim P_\theta} \left\{ \left[ K(X, X') - \frac{1}{n} \sum_{i=1}^n K(X_i, X) \right] \nabla_\theta [\log p_\theta(X)] \right\} \end{aligned}$$

that can be approximated by sampling from  $P_\theta$ .



## Example : Gaussian mean estimation

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$$\mathbb{D}_k^2(P_\theta, P_{\theta'}) = 2 \left( \frac{\gamma^2}{4\sigma^2 + \gamma^2} \right)^{\frac{d}{2}} \left[ 1 - \exp \left( -\frac{\|\theta - \theta'\|^2}{4\sigma^2 + \gamma^2} \right) \right]$$

we obtain

$$\begin{aligned} \mathbb{E} \left[ \|\hat{\theta}_n^{MMD} - \theta_0\|^2 \right] \\ \leq -(4\sigma^2 + \gamma^2) \log \left[ 1 - 4 \left( \frac{1}{n} + \varepsilon^2 \right) \left( \frac{4\sigma^2 + \gamma^2}{\gamma^2} \right)^{\frac{d}{2}} \right]. \end{aligned}$$

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we obtain

$$\mathbb{E} \left[ \|\hat{\theta}_n^{MMD} - \theta_0\|^2 \right] \lesssim d\sigma^2 \left( \frac{1}{n} + \varepsilon^2 \right).$$

# Example : Gaussian mean estimation, simulations

Model :  $\mathcal{N}(\theta, 1)$ , and  $X_1, \dots, X_n$  i.i.d  $\mathcal{N}(\theta_0, 1)$ ,  $n = 100$  and we repeat the experiment 200 times.

	$\hat{\theta}_n^{MLE}$	$\hat{\theta}_n^{MMD}$
mean absolute error	0.0722	0.0838

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Now,  $\varepsilon = 1\%$  are replaced by 1,000.

mean absolute error	10.018	0.0903
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# Going beyond toy examples



Dziugaite, G. K., Roy, D. M., & Ghahramani, Z. (2015). Training generative neural networks via maximum mean discrepancy optimization. *UAI 2015*.



Li, Y., Swersky, K. & Zemel, R. (2015). Generative moment matching networks. *ICML 2015*.

From the first reference :





# MMD-Bayes

Given a prior  $\pi(\theta)$  we propose the following **pseudo-posterior** :

$$\pi_\alpha(\theta|X_1, \dots, X_n) \propto e^{-\alpha \mathbb{D}_K^2(P_\theta, \hat{P}_n)} \pi(\theta).$$

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$$\pi_\alpha(\theta | X_1, \dots, X_n) \propto e^{-\alpha \mathbb{D}_K^2(P_\theta, \hat{P}_n)} \pi(\theta).$$

We also define a **variational approximation** for this. Given a set  $\mathcal{F}$  of probability distributions,

$$\hat{\pi}_\alpha(\theta) = \arg \min_{q \in \mathcal{F}} \mathcal{K}[q, \pi_\alpha(\cdot | X_1, \dots, X_n)].$$

# Bayesian MMD-based estimation

## Theorem - Chérif-Abdellatif + PA

Let  $\mathcal{B} = \{\theta \in \Theta / \mathbb{D}_K(P_{\theta_0}, P_\theta) \leq 1/\sqrt{n}\}$ . Assume  $(\pi, \alpha)$  satisfies the prior mass condition :  $\pi(\mathcal{B}) \geq e^{-\alpha/\sqrt{n}}$ . Then :

$$\mathbb{E} \left[ \int \mathbb{D}_K(P_\theta, P^0) \pi_n^\beta(d\theta) \right] \leq 4 \inf_{\theta \in \Theta} \mathbb{D}_K(P_\theta, P^0) + \frac{4}{\sqrt{n}}.$$

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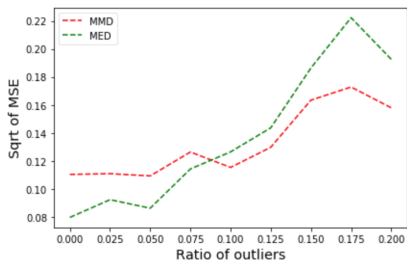
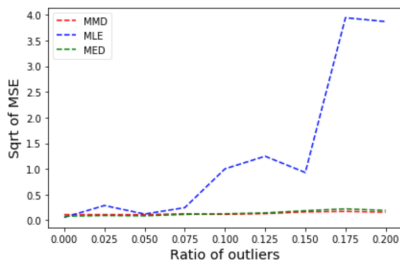
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A similar result holds for the variational approximation.

# Experiments in the Gaussian model



Thank you !